

Neurocomputing

Neurons

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https://www.verywellmind.com/what-is-a-neuron-2794890



- neurons.



http://bcs.whfreeman.com/webpub/Ektron/Hillis%20Principles%20of%20Life2e/Ani

https://en.wikipedia.org/wiki/Neuron

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• The human brain is composed of 100 billion

• A biological neuron is a cell, composed of a cell body (soma), multiple dendrites and an axon.

• The axon of a neuron can contact the dendrites of another through synapses to transmit information.

• There are hundreds of different types of neurons, each with different properties.



https://en.wikipedia.org/wiki/Action_potential

- Neurons are negatively charged: they have a resting potential at around -70 mV.
- When a neuron receives enough input currents, its membrane potential can exceed a threshold and the neuron emits an action potential (or spike) along its axon.
- A spike has a very small duration (1 or 2 ms) and its amplitude is rather constant.
- It is followed by a **refractory period** where the neuron is hyperpolarized, limiting the number of spikes per second to 200.





- - GABA

 - serotonin
 - nicotin
 - etc...

https://en.wikipedia.org/wiki/Neuron

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• The action potential arrives at the synapses and releases **neurotransmitters** in the synaptic cleft:

glutamate (AMPA, NMDA)

dopamine

• Neurotransmitters can enter the receiving neuron through **receptors** and change its potential: the neuron may emit a spike too.

• Synaptic currents change the membrane potential of the post.synaptic neuron.

• The change depends on the strength of the synapse called the **synaptic efficiency** or **weight**.

 Some synapses are stronger than others, and have a larger influence on the post-synaptic cell.

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Information is transmitted through spike trains



Source: https://en.wikipedia.org/wiki/Neural_oscillation

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- spike timing.
- lacksquare

• The two important dimensions of the information exchanged by neurons are:

The instantaneous frequency or firing rate: number of spikes per second (Hz).

• The precise **timing** of the spikes.

• The shape of the spike (amplitude, duration) does not matter much.

• Spikes are binary signals (0 or 1) at precise moments of time.

Some neuron models called rate-coded models only represent the firing rate of a neuron and ignore

Other models called **spiking models** represent explicitly the spiking behavior.

The Hodgkin-Huxley neuron (Hodgkin and Huxley, 1952)





- squid neuron.

- currents.

https://en.wikipedia.org/wiki/Hodgkin%E2%80%93Huxley_model

• Alan Hodgkin and Andrew Huxley (Nobel prize 1963) were the first to propose a detailed mathematical model of the giant

• The membrane potential V of the neuron is governed by an electrical circuit, including sodium and potassium channels.

• The membrane has a **capacitance** C that models the dynamics of the membrane (time constant).

• The **conductance** g_L allows the membrane potential to relax back to its resting potential E_L in the absence of external

• For electrical engineers: it is a simple RC network...

• External currents (synaptic inputs) perturb the membrane potential and can bring the neuron to fire an action potential.

The Hodgkin-Huxley neuron (Hodgkin and Huxley, 1952)

• Their model include:

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- An ordinary differential equation
 (ODE) for the membrane potential v.
- Three ODEs for n, m and h representing potassium channel activation, sodium channel activation, and sodium channel inactivation.
- Several parameters determined experimentally.
- Not only did they design experiments to find the parameters, but they designed the equations themselves.

$$\left\{egin{aligned} &a_n = 0.01 \, (v+60)/(1.0-\exp(-0.1 \, (v+60)))\ &a_m = 0.1 \, (v+45)/(1.0-\exp(-0.1 \, (v+45)))\ &a_h = 0.07 \, \exp(-0.05 \, (v+70))\ &b_n = 0.125 \, \exp(-0.0125 \, (v+70))\ &b_m = 4 \, \exp(-(v+70)/80)\ &b_h = 1/(1+\exp(-0.1 \, (v+40))) \end{aligned}
ight.$$

$$\begin{bmatrix}
\frac{dn}{dt} \\
\frac{dn}{dt} \\
\frac{dn}{dt} \\
\frac{dn}{dt}
\end{bmatrix}$$

$$C\,rac{dv}{dt}=g_L\,(V_L-v)+g_K\,n^4\,(V_K-v)+$$

$$rac{n}{t}=a_n\left(1-n
ight)-b_n\,n$$

$$rac{m}{lt} = a_m \left(1-m
ight) - b_m \, m$$

$$rac{h}{t}=a_{h}\left(1-h
ight) -b_{h}\,h$$

 $g_{
m Na}\,m^3\,h\,(V_{
m Na}-v)+I$

The Hodgkin-Huxley neuron (Hodgkin and Huxley, 1952)

• These equations allow to describe very precisely how an action potential is created from external currents.

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The leaky integrate-and-fire neuron (Lapicque, 1907)

- As action potentials are stereotypical, it is a waste of computational resources to model their generation precisely.
- What actually matters are the **sub-threshold** dynamics, i.e. what happens before the spike is emitted.
- The **leaky integrate-and-fire** (LIF) neuron integrates its input current and emits a spike if the membrane potential exceeds a threshold.

$$C\,rac{dv}{dt}=-g_L\,(v-V_L)+I$$

if $v > V_T$ emit a spike and reset.

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0 membrane potential v (mV) -10-20 -30 -40 -50 -60-70





Different spiking neuron models are possible

Izhikevich quadratic IF (Izhikevich, 2001).

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 Adaptive exponenti 2005).

$$egin{aligned} rac{dv}{dt} &= 0.04\,v^2 + 5\,v + 140 - u + I & C\,rac{dv}{dt} &= -g_L\,(v-E_L) + g_L\,\Delta_T\,\exp(rac{v-v_T}{\Delta_T}) & + I - w & \ & + I - w & \ & au_w\,rac{dw}{dt} &= a\,(v-E_L)\, \ & au_w$$



• Adaptive exponential IF (AdEx, Brette and Gerstner,

Realistic neuron models can reproduce a variety of dynamics



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Biological neurons do not all respond the same to an input current.

- Some fire regularly.
- Some slow down with time.
- Some emit bursts of spikes.

Modern spiking neuron models allow to recreate these dynamics by changing a few parameters.

Populations of spiking neurons



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- ullet
- population?
- ullet
- single neuron.

Interconnected networks of spiking neurons tend to fire synchronously (redundancy).

• What if the important information was not the precise spike timings, but the **firing rate** of a small

The instantaneous firing rate is defined in Hz (number of spikes per second).

• It can be estimated by an histogram of the spikes emitted by a network of similar neurons, or by repeating the same experiment multiple times for a

• One can also build neural models that directly model the **firing rate** of (a population of) neuron(s): the rate-coded neuron.

The rate-coded neuron

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- A rate-coded neuron is represented by two time-dependent variables:
 - The "membrane potential" v(t) which evolves over time using an ODE.
 - The firing rate r(t) which transforms the membrane potential into a single continuous value using a transfer function or activation function.



• The membrane potential uses a weighted sum of inputs (the firing rates $r_i(t)$ of other neurons) by multiplying each rate with a weight w_i and adds a constant value b (the bias). The activation function can be any non-linear function, usually making sure that the firing rate is positive.

Rate-coded neuron

The rate-coded neuron

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- When v(t) is quite different from I(t), the membrane potential "accelerates" to reduce the difference.
- When v(t) is similar to I(t), the membrane potential stays constant.

- Let's consider a simple rate-coded neuron taking a step signal I(t) as input:

$$egin{aligned} & au \, rac{dv(t)}{dt} + v(t) = I(t) \ & au(t) = (v(t))^+ \end{aligned}$$

• The "speed" of v(t) is given by its temporal derivative:

$$rac{dv(t)}{dt} = rac{I(t)-v(t)}{ au}$$

al "accelerates" to reduce the difference. nstant.

The rate-coded neuron

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- ullet

• The membrane potential follows an exponential function which tries to "match" its input with a speed determined by the **time constant** τ .

• The time constant τ determines how fast the ratecoded neuron matches its inputs.

Biological neurons have time constants between 5 and 30 ms depending on the cell type.

Activation functions

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Rectifier activation function

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• When using the rectifier activation function

$$f(x) = \max(0, x)$$

the membrane potential v(t) can take any value, but the firing rate r(t) is only positive.



Logistic activation function

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• When using the logistic (or sigmoid) activation function

$$f(x) = rac{1}{1 + \exp(-x)}$$

the firing rate r(t) is bounded between 0 and 1, but responds for negative membrane potentials.



x)

Networks of rate-coded neurons

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• Networks of interconnected rate-coded neurons can exhibit very complex dynamics (e.g. reservoir computing).

$$aurac{dv(t)}{dt} + v(t) = \sum_{ ext{input}} w^{ ext{I}} I(t) + g \sum_{ ext{rec}} w^{ ext{R}} r(t) + \xi(t)$$

$$r(t) = \tanh(v(t))$$



The McCulloch & Pitts neuron (McCulloch and Pitts, 1943)

• By omitting the dynamics of the rate-coded neuron, one obtains the very simple artificial neuron:

- The weighted sum of inputs + bias $\sum_{i=1}^d w_i x_i + b$ is called the net activation.
- This overly simplified neuron model is the basic unit of the artificial neural networks (ANN) used in machine learning / deep learning.

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$$y=f(\sum_{i=1}^d w_i\,x_i+b)$$

• An artificial neuron sums its inputs x_1, \ldots, x_d by multiplying them with weights w_1, \ldots, w_d , adds a bias b and transforms the result into an output yusing an activation function f.

• The output y directly reflects the input, without temporal integration.

Artificial neurons and hyperplanes

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- Let's consider an artificial neuron with only two inputs x_1 and x_2 .
- The net activation $w_1 \, x_1 + w_2 \, x_2 + b$ is the equation of a line in the space (x_1, x_2) .

 $w_1\,x_1+w_2\,x_2+b=0 \Leftrightarrow x_2=-$

$$-rac{w_1}{w_2}\,x_1-rac{b}{w_2}$$

Artificial neurons and hyperplanes

https://newvitruvian.com/explore/vector-planes/#gal_post_7186_nonzerovector.gif

- The net activation defines a line in 2D, a plane in 3D, etc.
- Generally, the net activation describes an **hyperplane** in the input space with d dimensions $(x_1, x_2, \ldots, x_d).$
- An hyperplane has one dimension less than the space.

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- vector w.

• We can write the net activation using a **weight** vector w and a bias b:

$$\sum_{i=1}^d w_i \, x_i + b = \langle \mathbf{w} \cdot \mathbf{x}
angle + b$$
 $\mathbf{w} = egin{bmatrix} w_1 \ w_2 \ \cdots \ w_d \end{bmatrix} \quad \mathbf{x} = egin{bmatrix} x_1 \ x_2 \ \cdots \ x_d \end{bmatrix}$

 $\langle \cdot \rangle$ is the **dot product** (aka inner product, scalar product) between the **input vector** \mathbf{x} and the weight

The weight vector is orthogonal to the hyperplane (\mathbf{w}, b) and defines its orientation. b is the "signed" distance" between the hyperplane and the origin.

Artificial neurons and hyperplanes

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- The hyperplane separates the input space into two parts:
 - $\langle \mathbf{w} \cdot \mathbf{x} \rangle + b > 0$ for all points \mathbf{x} above the hyperplane.
 - $\langle {f w}\cdot{f x}
 angle+b<0$ for all points ${f x}$ below the hyperplane.
- By looking at the **sign** of the net activation, we can separate the input space into two classes.

Overview of neuron models

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Biological plausibility

neuroscience

Neurocomputing

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