



UNIVERSITY OF TECHNOLOGY
IN THE EUROPEAN CAPITAL OF CULTURE
CHEMNITZ

Neurocomputing

Diffusion Probabilistic Models

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1 - Diffusion probabilistic models

Generative modeling

1D example:
we illustrate the
effect of G over
the entire
distribution

*Generative model
to be learned*

*Simple 1D gaussian
distribution we know
how to sample from*

*Targeted complex 1D
distribution we don't know
how to sample from*



**High dimension
example:**
we illustrate the
effect of G over a
single sample

*Generative model
to be learned*

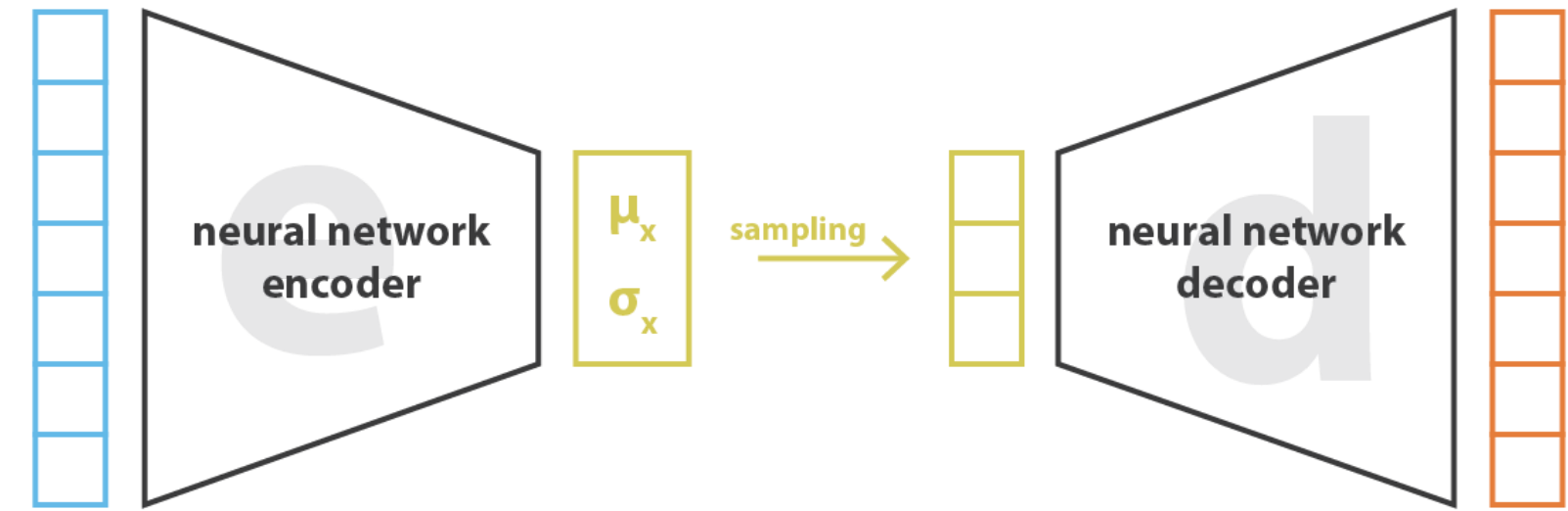
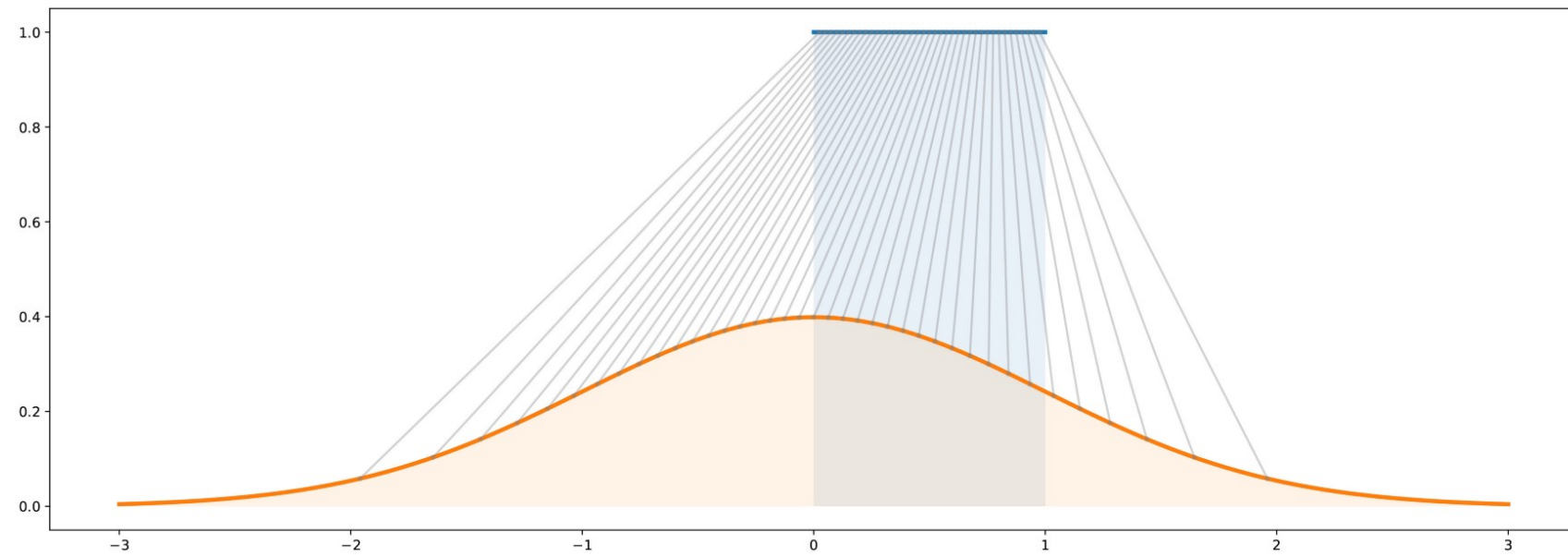
*High dimension data
point from simple
noise distribution*

*High dimension data
point from complex
image distribution*



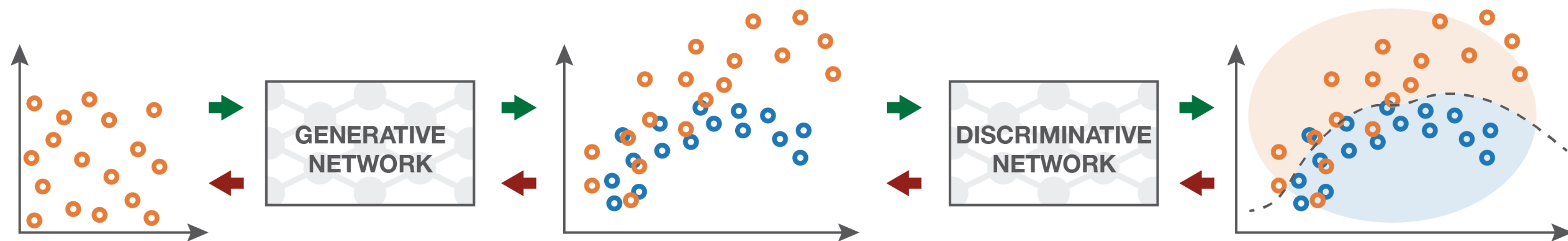
Source: <https://towardsdatascience.com/understanding-diffusion-probabilistic-models-dpms-1940329d6048>

VAE and GAN generators transform simple noise to complex distributions



■ Forward propagation (generation and classification)

■ Backward propagation (adversarial training)



Input random variables.

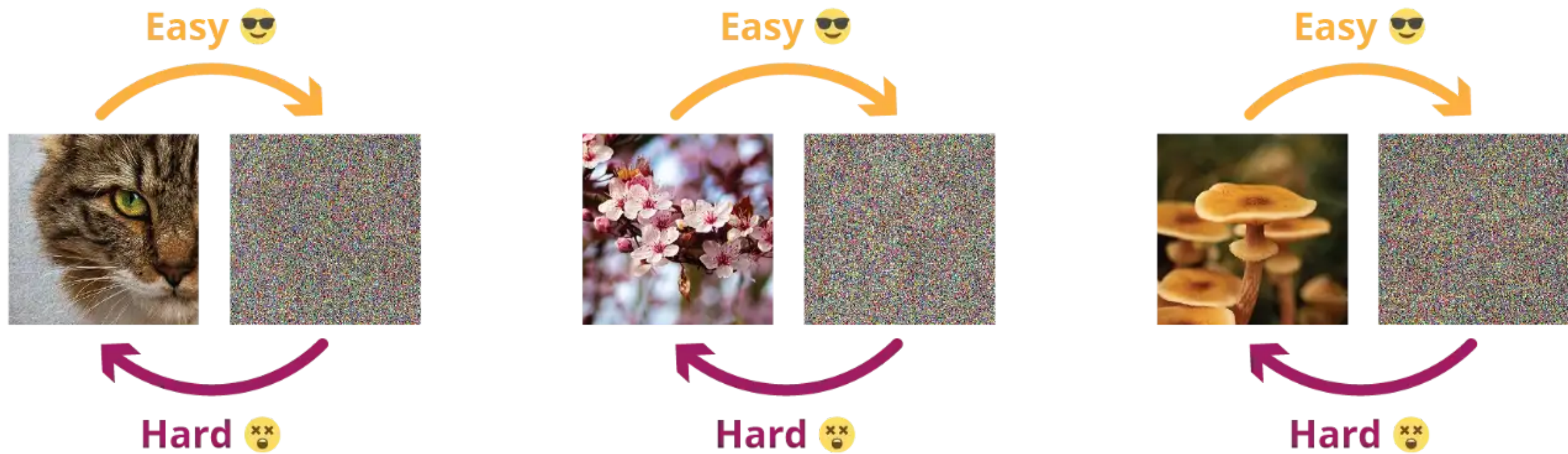
The generative network is trained to **maximise** the final classification error.

The **generated distribution** and the **true distribution** are not compared directly.

The discriminative network is trained to **minimise** the final classification error.

The classification error is the basis metric for the training of both networks.

Destroying information is easier than creating it



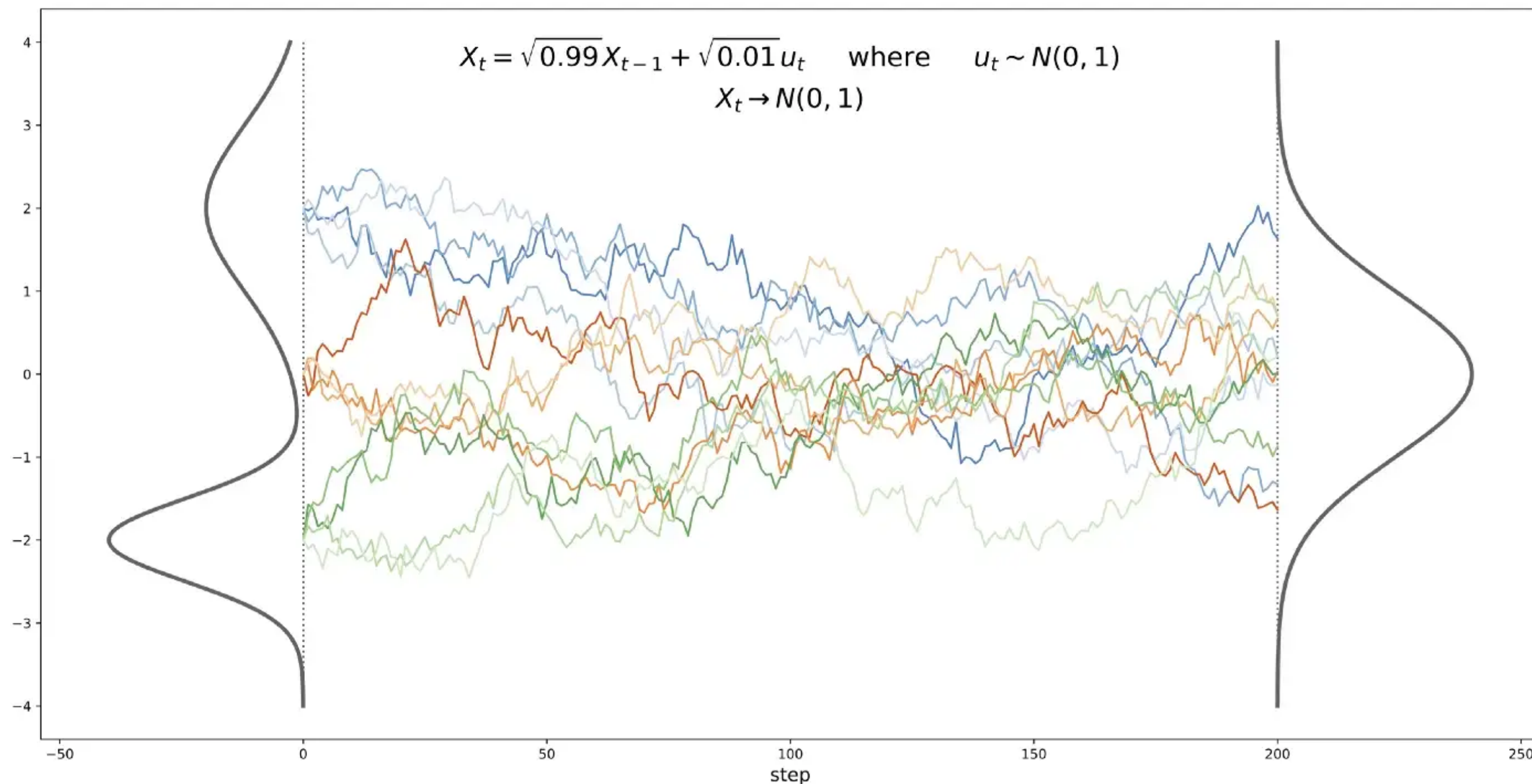
Source: <https://towardsdatascience.com/understanding-diffusion-probabilistic-models-dpms-1940329d6048>

Stochastic processes can destroy information

- Iteratively adding normal noise to a signal creates a **stochastic differential equation** (SDE).

$$X_t = \sqrt{1-p} X_{t-1} + \sqrt{p} \sigma \quad \text{where} \quad \sigma \sim \mathcal{N}(0, 1)$$

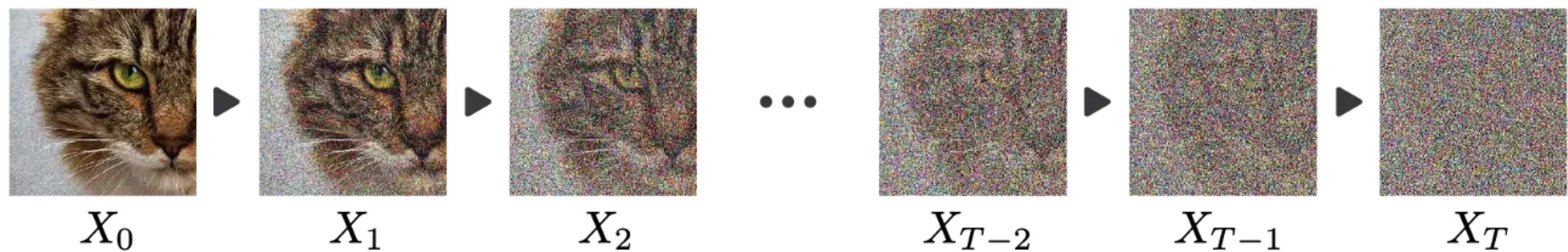
- Under some conditions, any probability distribution converges to a normal distribution.



Source: <https://towardsdatascience.com/understanding-diffusion-probabilistic-models-dpms-1940329d6048>

Diffusion process

- A **diffusion process** can iteratively destruct all information in an image through a Markov chain.



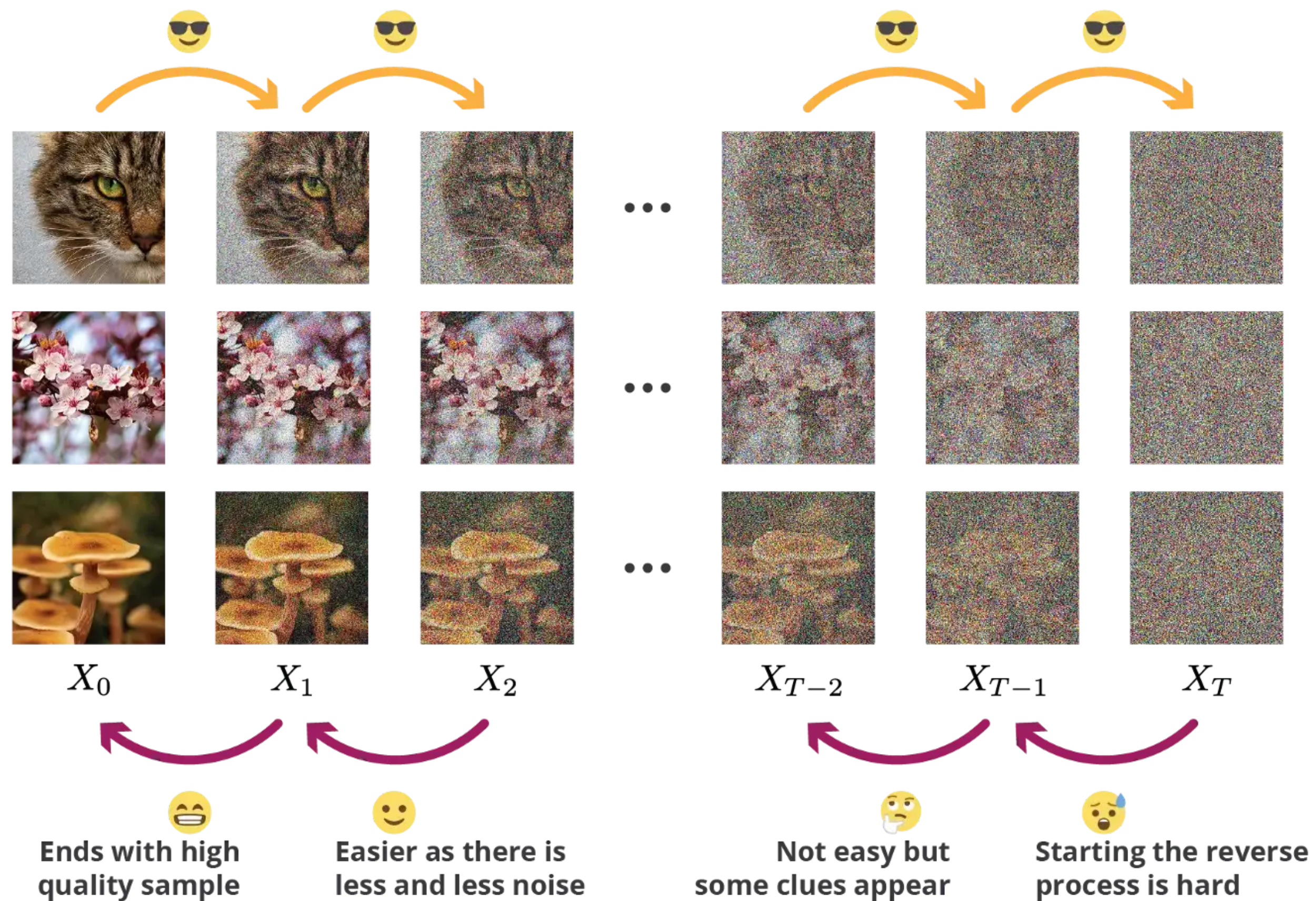
$$X_1 = \sqrt{1-p} X_0 + \sqrt{p} u_1 \quad u_1 \sim \mathcal{N}(0, I)$$

The equation shows the first step of the diffusion process. The image X_1 is equal to the original image X_0 scaled by $\sqrt{1-p}$, plus a noise vector u_1 scaled by \sqrt{p} . The noise vector u_1 is drawn from a standard normal distribution $\mathcal{N}(0, I)$.

Source: <https://towardsdatascience.com/understanding-diffusion-probabilistic-models-dpms-1940329d6048>

Reverse Diffusion process

- It should be possible to **reverse** each diffusion step by removing the noise using a form of denoising autoencoder.



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Reverse Diffusion process

- We will not get into details, but learning the reverse diffusion step implies Bayesian inference, KL divergence and so on.
- As we have the images at t and $t + 1$, it should be possible to learn, right?

FIXED FORWARD PROCESS

Initial distribution
 $q(x_0)$

Gaussian transition kernel
 $q(x_t|x_{t-1}) = \mathcal{N}(x_t; \sqrt{1 - \beta_t}x_{t-1}, \beta_t I)$



Approximation of
 $q(x_{t-1}|x_t)$

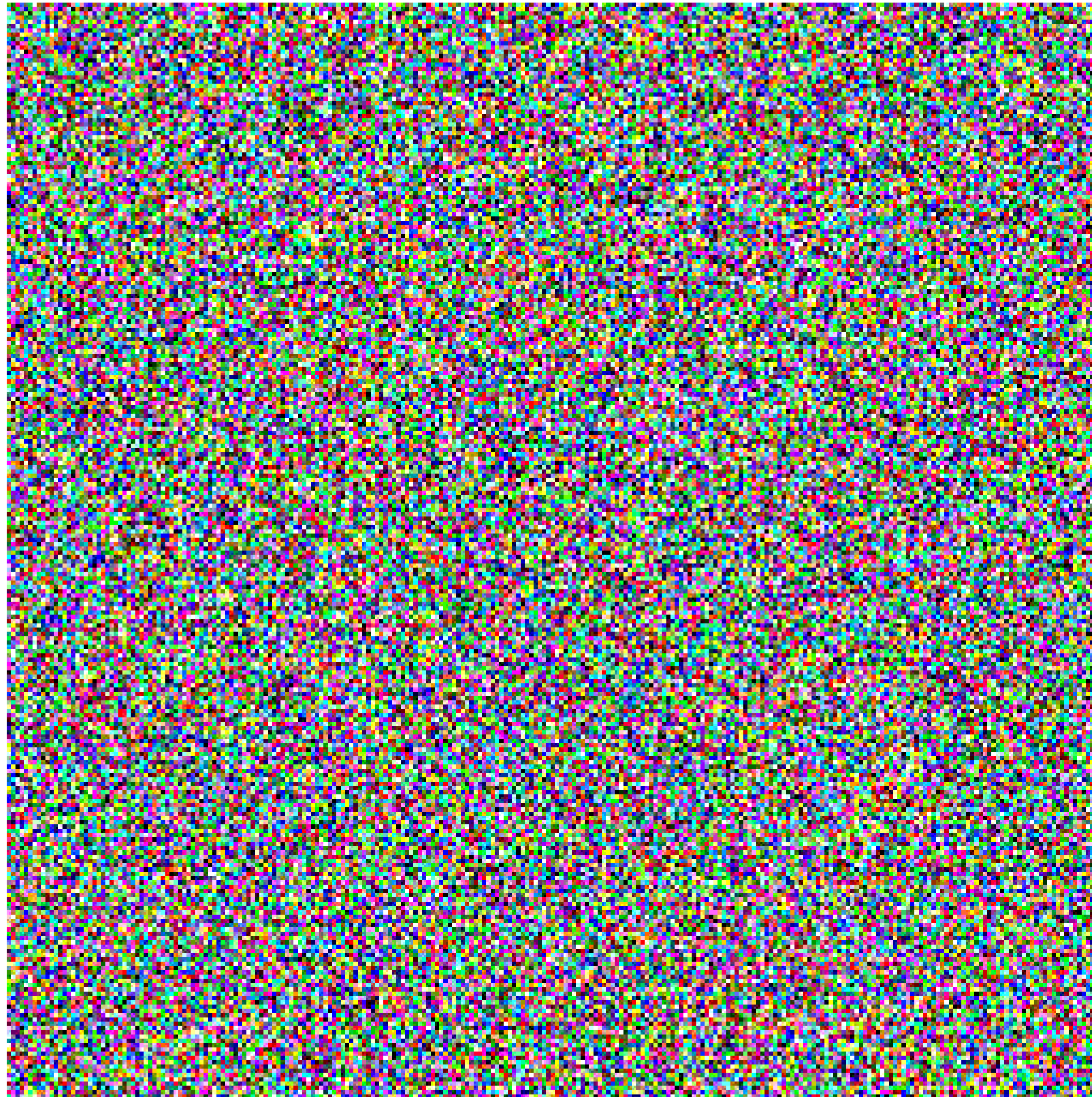
Gaussian transition kernel with parameters to be learned
 $p_\theta(x_{t-1}|x_t) = \mathcal{N}(x_{t-1}; \mu_\theta(x_t, t), \Sigma_\theta(x_t, t))$

Initial distribution
 $p(x_T) = \mathcal{N}(x_t; 0, I)$

LEARNED BACKWARD PROCESS

Source: <https://towardsdatascience.com/understanding-diffusion-probabilistic-models-dpms-1940329d6048>

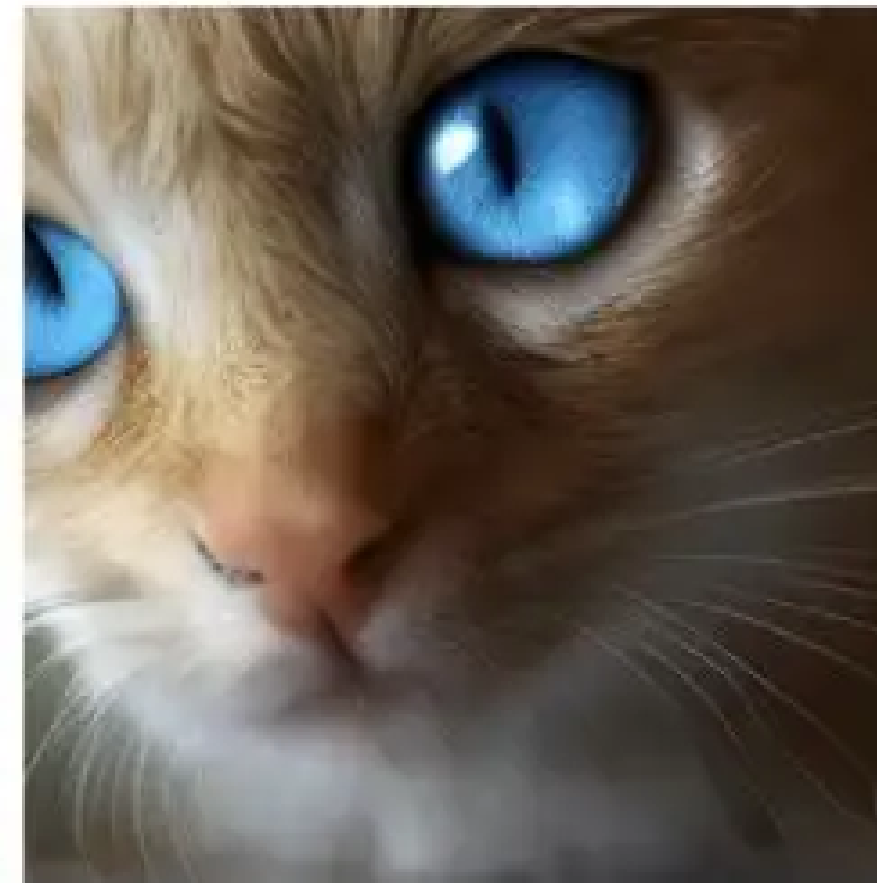
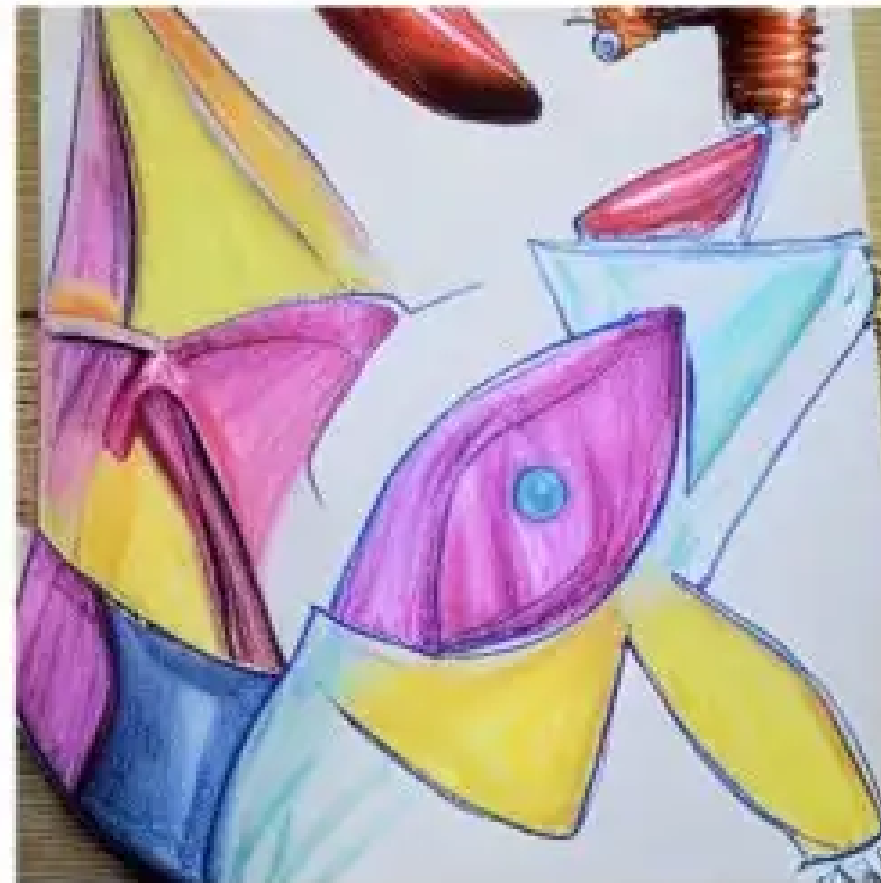
Probabilistic diffusion models



Source: <http://adityamesh.com/posts/dalle2/dalle2.html>

2 - Dall-e

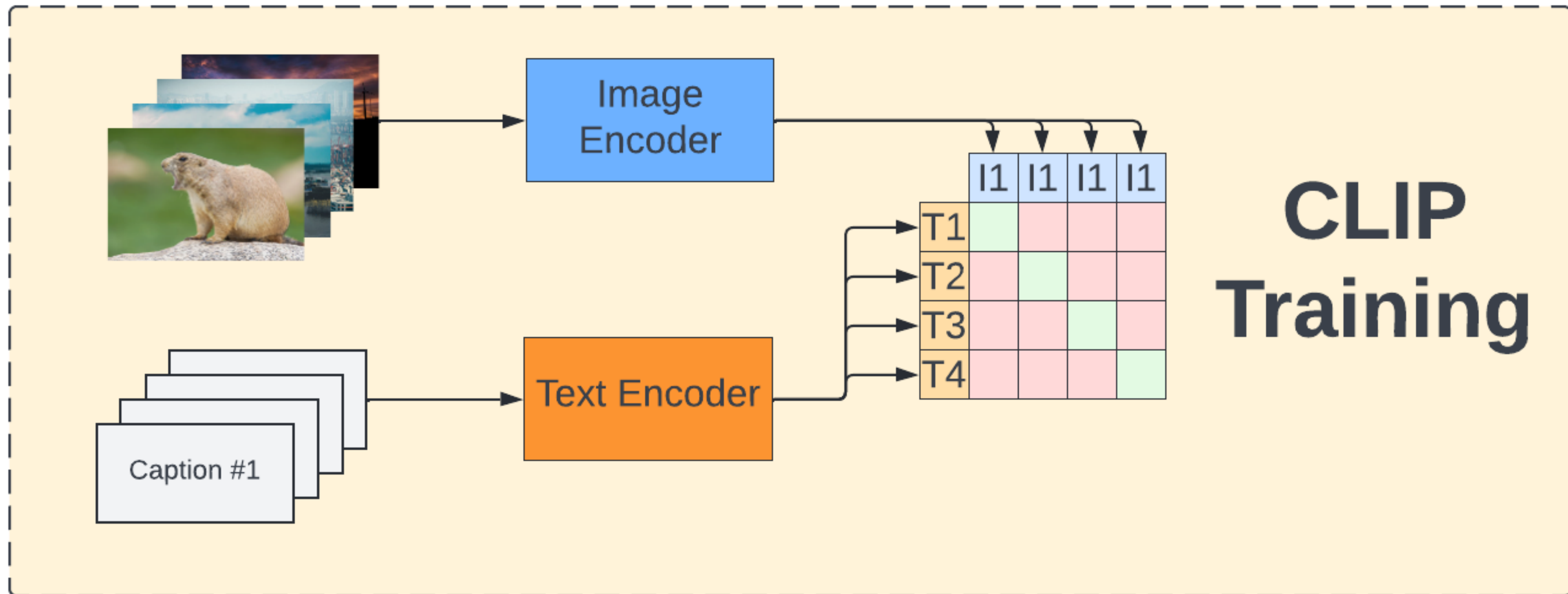
Dall-e



Source: <https://towardsdatascience.com/understanding-diffusion-probabilistic-models-dpms-1940329d6048>

CLIP: Contrastive Language-Image Pre-training

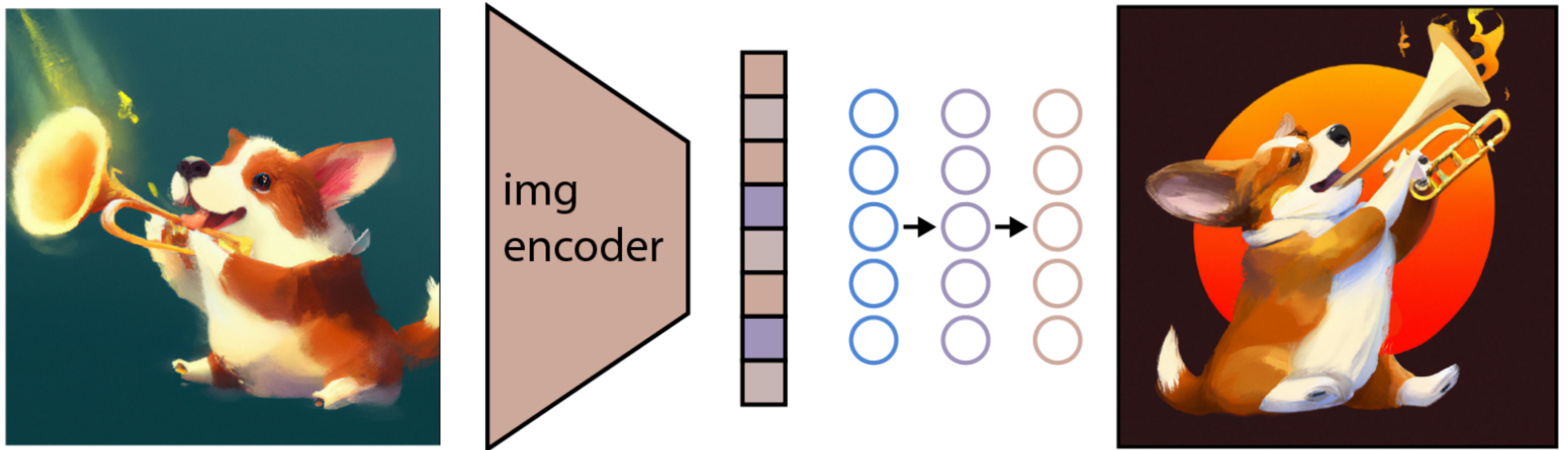
- Embeddings for text and images are learned using **Transformer encoders** and **contrastive learning**.
- For each pair (text, image) in the training set, their representation should be made similar, while being different from the others.



Source: <https://towardsdatascience.com/understanding-how-dall-e-mini-works-114048912b3b>

GLIDE

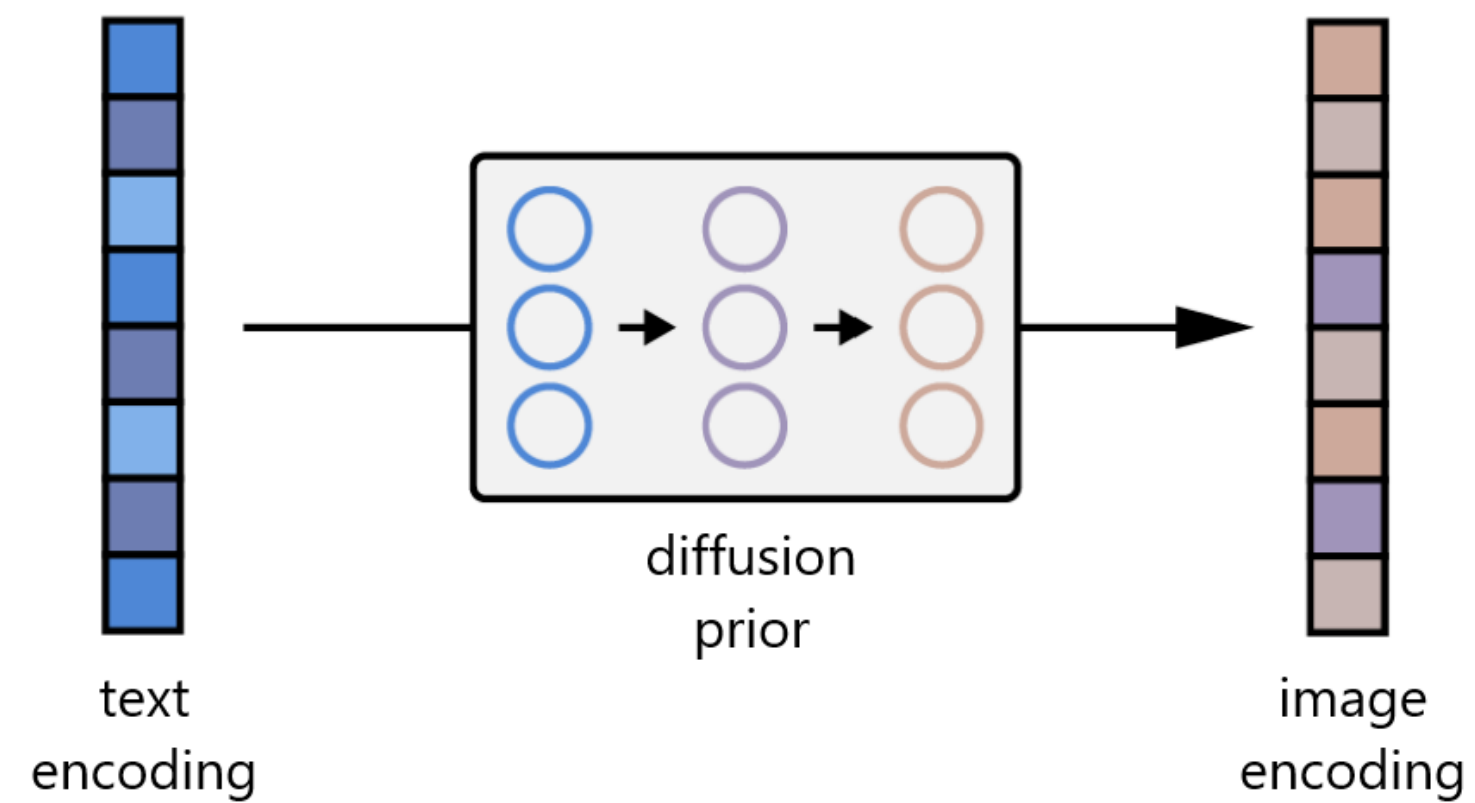
- GLIDE is a **reverse diffusion process** conditioned on the encoding of an image.



Source: <https://www.assemblyai.com/blog/how-dall-e-2-actually-works/>

Dall-e

- A prior network learns to map text embeddings to image embeddings:



Source: <https://www.assemblyai.com/blog/how-dall-e-2-actually-works/>

- Complete Dall-e architecture:

